Computer Science 331 Quicksort

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Lecture #28

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Outline

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 - Randomized Partitioning
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Introduction

Introduction

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Idea

- **Quicksort:**
 - A recursive "Divide and Conquer" sorting algorithm
 - A simple deterministic version uses
 - $\Theta(n^2)$ operations to sort an array of size *n* in the worst case
 - $\Theta(n \log n)$ operations on average, assuming all relative orderings of the (distinct) input are equally likely
 - The expected number of operations used by a randomized version is in $O(n \log n)$ for any input array of size n
 - Reference: Introduction to Algorithms, Chapter 7. This textbook discusses a different version of this algorithm.

Choose an element x and reorder the array as follows:

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- x is in the correct spot if the array was sorted
- elements < x are to the left of x in the array
- elements > x are to the right of x in the array
- 2 Recursively sort subarray of elements to the left of x
- Recursively sort subarray of elements to the right of x

Step 1 is the key to this method being efficient. Issues:

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Deterministic Partitioning

Partitioning

A procedure that is called repeatedly by the main Quicksort algorithm (Step 1 in the previous description)

Objective: Reorder the values in a given portion of the array so that

- all values less than or equal to some "pivot element" are at the beginning, and
- all values greater than this pivot element are at the end.

Return the location of the pivot element as output

Number of operations used is linear in the length of the part of the array that is being processed

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Deterministic Partitioning

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Deterministic Partitioning

Pseudocode

```
DPartition(A, p, r)
{Assumption: 0 }
x = A[r]
i = p - 1; j = p
while j < r do
  if A[j] \leq x then
    i = i + 1
    Swap: tmp = A[i]; A[i] = A[j]; A[j] = tmp
  end if
  j = j + 1
end while
Swap: tmp = A[i + 1]; A[i + 1] = A[r]; A[r] = tmp
return i+1
```

Deterministic Partitioning

Idea:

- Pivot element used is the last element in the part of the array being processed. Other versions of this algorithm use the first element instead.
- Sweep from left to right over the array, exchanging elements as needed, so that values less than or equal to the pivot element are all located before values that are greater than the pivot element, in the part of the array that has been processed

Example

Consider the execution of **DPartition**(A, 3, 10) for A as follows:

Using x = A[10] = 5 as the pivot. Initially i = 2, j = 3.

i = 3:

i = 4:

Deterministic Partitioning

Example (cont.)

i = 5:

$$i = , j =$$
 3 4 5 6 7 8 9 10 ...

i = 6:

$$i = , j =$$
 3 4 5 6 7 8 9 10 ...

i = 7:

$$i = , j =$$
 3 4 5 6 7 8 9 10 ...

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Partitioning Deterministic Partitioning

Partial Correctness: Loop Invariant

Suppose p and r are integers such that 0 .

If $k \ge 0$ and the for-loop is executed at least k times, then the following conditions are satisfied at the **beginning** of the k^{th} execution of the loop body:

- $0 \quad j \in \mathbb{Z}, p \le j \le r-1, \text{ and } j = p+k.$
- ② $i \in \mathbb{Z}$, and p 1 < i < j 1.
- **3** The following hold for each integer ℓ such that $p < \ell < r$:
 - If $p \le \ell \le i$ then $A[\ell] \le x$.
 - If $i + 1 < \ell < j 1$ then $A[\ell] > x$.
 - If $\ell = r$ then $A[\ell] = x$.
- Entries of A are reordered but otherwise unchanged.

Note: At the *end* of this execution of the loop body, either j = i + 1, or j > i + 1 and A[j] > x as well.

Example (cont.)

i = 8:

Deterministic Partitioning

i = 9:

$$i = , j =$$
 $\frac{3 \ 4 \ 5 \ 6 \ 7 \ 8 \ 9 \ 10 }{ \dots }$

j = 10:

$$i = , j =$$
 3 4 5 6 7 8 9 10 ...

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Partitioning Deterministic Partitioning

Partial Correctness: Application of Loop Invariant

Once again, suppose that p and r are integers such that $0 \le p \le r < \text{length}(A)$. Let x be the value that was stored at location r of A before the program was called.

If the program halts then the following conditions are satisfied on termination (that is, when the **return** statement is executed):

- 2 The following relationships hold for each integer ℓ such that $p \le \ell \le r$:
 - If $p < \ell < i$ then $A[\ell] < x$.
 - If $\ell = i + 1$ then $A[\ell] = x$.
 - If $i + 2 \le \ell \le r$ then $A[\ell] > x$.
- Entries of A are reordered but otherwise unchanged.

Randomized Partitioning

Randomized Partitioning

Termination and Efficiency

Loop Variant: r - i

Justification:

Application:

- The initial value of the loop variant is r pTherefore the loop body is executed exactly r - p times.
- Each execution of the loop body requires (at most) a constant number of operations.

Therefore the cost to execute the loop is in O(r - p).

 Since the rest of the program only uses a constant number of operations, it is clear that the program terminates and that it uses O(r-p) operations in the worst case.

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Randomized Partitioning: Analysis

Suppose p and r are integers such that $0 \le p \le r < \text{length}(A)$ and that RPartition is called with inputs A, p and r.

- This algorithm terminates using O(r p) operations.
- Let q be the value that is returned on termination. Then the following conditions hold on termination.
 - $p \le q \le r$.
 - If $\ell \in \mathbb{Z}$ and $p \le \ell < q$ then $A[\ell] \le A[q]$.
 - If $\ell \in \mathbb{Z}$ and $q < \ell < r$ then $A[\ell] > A[q]$.

If the entries on A are distinct then q = i with probability r - p + 1for each integer *i* between *p* and *r* (inclusive).

• Entries of A are reordered but otherwise unchanged.

Idea: Choose the pivot element randomly from the set of values in the part of the array to be processed. Then proceed as before.

```
RPartition(A, p, r)
{Assumption: 0 \le p \le r < \text{length}(A)}
Choose i randomly and uniformly from the set of integers between p
and r (inclusive).
Exchange: tmp = A[i]; A[i] = A[r]; A[r] = tmp
return DPartition(A, p, r)
```

Deterministic Quicksort

Deterministic Quicksort

Idea: Partition the array, then recursively sort the pieces before and after the pivot element.

Call **quickSort**(A, 0, length(A) – 1) to sort A:

```
quickSort(A, p, r)
if p < r then
   q = \mathbf{DPartition}(A, p, r)
   quickSort(A, p, q-1)
   quickSort(A, q + 1, r)
end if
```

Randomized Quicksort

Idea: Same as deterministic Quicksort, except that randomized partitioning is used.

Call **RQuicksort**(A, 0, length(A) – 1) to sort A:

```
RQuicksort(A, p, r)
if p < r then
  q = RPartition(A, p, r)
  RQuicksort(A, p, q-1)
  RQuicksort(A, q + 1, r)
end if
```

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Worst-Case Analysis of Deterministic Quicksort

Theorem 2

If Deterministic Quicksort is applied to an array of length n whose entries are already sorted then this algorithm uses $\Omega(n^2)$ steps.

Method of Proof: Induction on *n*, once again.

Conclusion: Deterministic Quicksort uses $\Theta(n^2)$ to sort an array of length *n* in the worst case.

Worst-Case Analysis of Deterministic Quicksort

Theorem 1

Let *T*(*n*) be the number of steps used by QuickSort to sort an array of length n in the worst case. Then

$$T(n) \leq egin{cases} c_0 & \text{if } n \leq 1, \\ c_1 n + \max_{0 \leq k \leq n-1} \left(T(k) + T(n-1-k) \right) & \text{if } n \geq 2. \end{cases}$$

Justification: Base case requires constant # of steps. General case:

Application: This recurrence can be used to prove that $T(n) \in O(n^2)$ using induction on k.

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Average-Case Analysis of Deterministic Quicksort

Consider an application of this algorithm when the input is an array A with n distinct entries

Consider a binary search tree T storing the same values, with

- the "partition" element at the root
- the left subtree formed by considering the application of the algorithm to the left subarray
- the right subtree formed by considering the application of the algorithm to the right subarray

Useful Property: The number of steps used by the algorithm is at most

$$cn(height(T) + 1)$$

for some positive constant c

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Average-Case Analysis of Deterministic Quicksort

Assumption for Analysis: Entries of *A* are distinct and all *n*! relative orderings of these inputs are equally likely

Useful Property: The corresponding binary search trees *T* are generated with the probability distribution discussed in the "Average Case Analysis of Binary Search Trees."

Bounds on expected height of trees from those notes can now be applied.

Conclusion: The expected cost of Quicksort is in $O(n \log n)$ if the above assumption for analysis is valid.

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An Annoying Problem

An Annoying Problem: Both versions of Quicksort, given above, use $\Theta(n^2)$ operations to "sort" an array of length n if the array contains n copies of the same value!

The different version of Quicksort found in the textbook has the same problem!

The tutorial exercises on quickSort discuss a modification to partition that addresses this problem.

Analysis of Randomized Quicksort

The previous analysis can be modified to establish that the "worst-case expected cost" of Randomized Quicksort to sort an array with distinct **entries** is in $O(n \log n)$ as well.

Note: it is possible to obtain a *worst-case* running time of $\Theta(n \log n)$

• careful (but deterministic) selection of the pivot (see *Introduction* to Algorithms, Chapter 9.3)

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References

References:

 Cormen, Leiserson, Rivest and Stein Introduction to Algorithms, Second Edition

Chapter 7 includes more details, including a complete analysis of the version of Quicksort presented here

Textbook

Section 10.9 presents a Quicksort algorithm and analysis. Two different "partition" algorithms with the same asymptotic cost are presented.