

Introduction

Merge Sort is is an asymptotically faster algorithm than the sorting algorithms we have seen so far.

It can be used to sort an array of size *n* using ⊖(*n*log<sub>2</sub> *n*) operations in the worst case.

Presented here: A version that takes an input array *A* and produces another sorted array *B* (containing the entries of *A*, rearranged)

A solution to the "Merging Problem" (presented next) is a subroutine that is used to do much of the work.

Reference: Textbook, Section 10.7

# Merging Description The "Merging" Problem

Calling Sequence:  $merge(A_1, A_2, B)$ 

Precondition:

•  $A_1$  is a sorted array of length  $n_1 \in \mathbb{N}$ , so that

 $A_1[h] \le A_1[h+1]$  for  $0 \le h \le n_1 - 2$ 

•  $A_2$  is a sorted array of length  $n_2 \in \mathbb{N}$ , so that

 $A_2[h] \le A_2[h+1] \qquad \text{for } 0 \le h \le n_2-2$ 

• Entries of  $A_1$  and  $A_2$  are objects of the same ordered type

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## The "Merging" Problem (cont.)

#### Postcondition:

• *B* is a sorted array of length  $n_1 + n_2$ , so that

 $B[h] \le B[h+1]$  for  $0 \le h \le n_1 + n_2 - 2$ 

- Entries of *B* are the entries of  $A_1$  together with the entries of  $A_2$ , reordered but otherwise unchanged
- A<sub>1</sub> and A<sub>2</sub> have not been modified

## Idea for an Algorithm

Maintain indices into each array (each initially pointing to the leftmost element)

#### repeat

- Compare the current elements of each array
- Append the smaller entry onto the "end" of *B*, advancing the index for the array from which this entry was taken

until one of the input arrays has been exhausted

Append the rest of the other input array onto the end of B

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Merging Description			Merging Description			
Pseudocode	Pseudocode, Continued					
$\begin{split} \textbf{merge}(A_1, A_2, B) \\ n_1 &= \textit{length}(A_1); \ n_2 = \textit{length}(A_2) \\ \textbf{Declare } B \text{ to be an array of length } n_1 + n_2 \\ i_1 &= 0; \ i_2 &= 0; \ j = 0 \\ \textbf{while}(i_1 < n_1) \text{ and } (i_2 < n_2) \text{ do} \\ \textbf{if } A_1[i_1] &\leq A_2[i_2] \text{ then} \\ B[j] &= A_1[i_1]; \ i_1 &= i_1 + 1 \\ \textbf{else} \\ B[j] &= A_2[i_2]; \ i_2 &= i_2 + 1 \\ \textbf{end if} \\ j &= j + 1 \\ \textbf{end while} \end{split}$		{Copy remainder of $A_1$ while $i_1 < n_1$ do $B[j] = A_1[i_1]; i_1 = i_1 -$ end while {Otherwise copy remain while $i_2 < n_2$ do $B[j] = A_2[i_2]; i_2 = i_2 -$ end while	(if any)} + 1; <i>j</i> = <i>j</i> + 1 inder of <i>A</i> <sub>2</sub> } + 1; <i>j</i> = <i>j</i> + 1			

## Example



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## Loop Invariant for Loop #1

After the  $k^{\text{th}}$  execution of the body of the first loop

- $n_1 = \text{length}(A_1) \in \mathbb{N}; n_2 = \text{length}(A_2) \in \mathbb{N}; i_1, i_2, j \in \mathbb{N};$
- $0 < i_1 < n_1$  and  $0 < i_2 < n_2$ ;
- $i = k = i_1 + i_2$ ;
- B[h] < B[h+1] for 0 < h < j-2;
- $B[0], B[1], \ldots, B[j-1]$  are the values

 $A_1[0], A_1[1], \ldots, A_1[i_1 - 1]$  and  $A_2[0], A_2[1], \ldots, A_2[i_2 - 1]$ ,

reordered but otherwise unchanged;

- if i > 1 and  $i_1 < n_1$  then  $B[i 1] < A_1[i_1]$
- if  $j \ge 1$  and  $i_2 < n_2$  then  $B[j 1] \le A_2[i_2]$
- The arrays  $A_1$  and  $A_2$  have not been changed.

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#### $f(n_1, n_2, j) = (n_1 - i_1) + (n_2 - i_2)$

Analysis for Loop #1, Concluded

**Loop Variant for Loop #1:**  $f(n_1, n_2, j) = n_1 + n_2 - j$ 

• loop invariant implies that  $i = i_1 + i_2$ , so that

• it follows, since  $i_1 \leq n_1$  and  $i_2 \leq n_2$ , that  $i_1 = n_1$  and  $i_2 = n_2$  if  $f(n_1, n_2, j) \leq 0$ 

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• Initial value of j = 0, so worst-case # of iterations is  $\leq n_1 + n_2$ 

Application of Loop Invariant and Loop Variant: failure of the loop test, and the loop invariant, implies that either  $i_1 = n_1$  or  $i_2 = n_2$  on termination of the first loop. Conclusion:

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#### Merging Analysis

## Analysis for Loop #2

### Loop Invariant for Loop #2:

Same as the loop invariant for loop #1, along with the additional condition

either 
$$i_1 = n_1$$
 or  $i_2 = n_2$ 

#### Loop Variant for Loop #2: Same as for loop #1.

#### **Conclusions:**

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## Analysis for Loop #3

#### Loop Invariant for Loop #3:

Same as the loop invariant for loop #1, along with the additional condition

 $i_1 = n_1$ 

#### Loop Variant for Loop #3: Same as for loop #1.

#### **Conclusions:**

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## Analysis of the Merging Algorithm

#### Correctness:

- loop invariants prove partial correctness (if merge terminates, the output is correct)
- loop variant implies that the for loops (and hence the entire algorithm) terminate
- therefore, merge is correct

#### Efficiency:

- Each of the three loops executes no more than  $n_1 + n_2$  times
- each loop body requires a constant number of steps
- total cost of **merge** is  $\Theta(n_1 + n_2)$

## Merge Sort: Idea for an Algorithm

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Merge Sort Description

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Suppose we:

- Split an input array into two roughly equally-sized pieces.
- 2 *Recursively* sort each piece.
- Merge the two sorted pieces.

This sorts the originally given array.

Note: this algorithm design strategy is known as divide-and-conquer.

- divide the original problem (sorting an array) into smaller subproblems (sorting smaller arrays)
- solve the smaller subproblems recursively
- combine the solutions to the smaller subproblems (the sorted subarrays) to obtain a solution to the original problem (merging the sorted arrays)

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#### Merge Sort Description

## Pseudocode



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## **Partial Correctness**

#### Theorem 1

If mergeSort is run on an input array A of size n, then either

 the algorithm eventually halts, producing the desired sorted array B as output,

or

• the algorithm does not halt at all.

#### Prove by induction on n

- prove partial correctness for n = 1
- prove partial correctness for n > 1 assuming partial correctness for arrays of size k for k < n</li>

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## **Proof of Partial Correctness**

Base Case: n = 1

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- if n = 1, array consists of one element (array is sorted trivially)
- algorithm returns B containing a copy of the single element in the array (terminates with correct output)

Inductive hypothesis:

• assume the algorithm is partially correct for arrays of size k < nProve that *B* is sorted under this assumption:

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#### Merge Sort Analysis

## Termination and Efficiency

Let T(n) be the number of steps used by this algorithm when given an input array of length *n*, in the worst case.

We can see the following by inspection of the code:

$$T(n) \leq egin{cases} c_0 & ext{if } n=1 \ T(\lceil n/2 \rceil) + T(\lfloor n/2 
floor) + c_1 n & ext{if } n \geq 2 \end{cases}$$

for some constants  $c_0$  and  $c_1$ .

Special Case: If  $n = 2^k$  is a power of two, we can rewrite this as

$$T(n) \leq egin{cases} c_0 & ext{if } n=1 \ 2T(n/2)+c_1n & ext{if } n\geq 2 \end{cases}$$

## Termination and Efficiency

### Theorem 2

If  $n = 2^k$  is a power of two, and  $c = \max(c_0, c_1)$ , then

$$T(n) \leq cn \log_2(2n) = cn(k+1)$$

Prove by induction on k

• Base case (k = 0): for k = 0 we have  $n = 2^0 = 1$ , and

$$T(1) = c_0 \le cn(k+1) = c$$

because  $c = \max(c_0, c_1)$ 

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Merge Sort Analysis			Merge Sort Analysis					
Termination and Efficiency		Termination and Efficiency (General Case)						
Inductive hypothesis: Assume $k > 0$ and theorem holds for $k - 1$ :		Consider the function $L(n) = \lceil \log_2 n \rceil$ for $n \ge 1$						
Show that the theorem holds for <i>k</i> :		Useful Property: • $L(\lceil n/2\rceil) = L(n) - 1$ and $L(\lfloor n/2\rfloor) \le L(n) - 1$ for every integer $n \ge 2$						
			Theorem 3 If $n \ge 1$ then $T(n) \le cnL(2n) \le cn(\log_2 n + 2)$ .					
			Method of Proof: induction on <i>n</i>					

#### Merge Sort Analysis

## Further Observations

It can be shown (by consideration of particular inputs) that the worst-case running time of this algorithm is also in  $\Omega(n \log_2 n)$ . It is therefore in  $\Theta(n \log_2 n)$ 

- This is preferable to the classical sorting algorithms, for sufficiently large inputs, if worst-case running time is critical
- The classical algorithms are *faster* on sufficiently *small* inputs because they are simpler

Alternative Approach: A "hybrid" algorithm:

- Use the recursive strategy given above when the input size is greater than or equal to some (carefully chosen) "threshold" value
- Switch to a simpler, nonrecursive algorithm (that is faster on small inputs) as soon as the input size drops to below this "threshold" value

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